

## Midterm 1 Study Guide

- Program performance
  - What aspects affect it and how
- Stored program concept, how was this revolutionary?
- Basic stored program execution flow (lec2, slide 6)
- RISC vs. CISC
  - Basic organization, how are they different?
  - Advantages and disadvantages
  - Where can operands come from? How is this advantageous for building RISC pipelines?
- MIPS
  - Registers
    - How many, how big, why are some special?
  - Instruction formats
    - What are they
    - Why only three
    - Advantages of fixed formatting/size
    - Why aren't all fields used? Advantages/disadvantages
    - Implications/side effects of changing a field size (e.g., changing the number of registers to 6 but leaving the instruction length fixed at 23-bits)
  - Support for procedure/function calls
    - How are arguments and return values handled
    - Temporary vs saved registers
    - Caller vs. callee saved registers
    - Return address?
    - Stack frame, what is in it and why is it useful
      - Frame pointer vs. stack pointer
  - Purpose of load linked and store conditional
  - Arithmetic vs. logical operations
  - Architectural structure
    - Advantages/disadvantages for speculative operations (e.g., fetching registers while the instruction is being decoded)
  - Instruction phases:
    - Instruction fetch, register fetch/instruction decode, execution/address calculation, memory access, register write back (e.g., Lec 6, slide 8)
    - What happens in each phase for each instruction type? High-level operation details based on the instruction being executed. I would not ask you to define signal values for datapath components
- Structural designs
  - Fast and big vs. small and slow
    - Implications
    - Advantages/disadvantages
    - Ex. Ripple carry vs. carry look ahead adders
    - How can this concept be applied to other structures
  - Single cycle (one long cycle) vs multi-cycle (multiple shorter cycles) designs for the same overall operation
    - Advantages/disadvantages
    - Multi-cycle vs. multiple-cycle delay path
    - Understand implications on the critical path for single vs. multi-cycle operation.
    - How does the clock cycle change? How does overall execution time of 1 instruction change? (not pipelined yet)
    - Maintaining timing constraints: different between single cycle violations and multi-cycle violations
- Processor design (note: simple designs for a small set of instructions)
  - Define datapath components based on a set of instructions

- Design an ALU based on a set of operations
  - Define a controller and datapath based on a set of instructions
  - Question 1 on the sample midterm is VERY IMPORTANT!
- Multipliers/Dividers
  - Iterative improvement purposes (what was being reduced)
    - Reasons why registers could be removed/combined, ALUs could be reduced
  - Know the basic progression of each version, but no details. I would remind you in the question of any details you needed to know
  - Work through an example for multiple/divide version 3
    - Show register values for each iteration
  - Booth's algorithm for multiply
    - What is the purpose of this algorithm
    - Basic idea of how it works
    - Do not need to work through an example
- Floating point
  - Convert a decimal number to binary single-precision floating point notation
  - Bias – what is it? What does it facilitate?
  - Single-precision vs. double precision
    - Ranges
    - Register layout
  - Exceptions
    - Underflow, overflow
    - Infinity, NaN
  - Decimal representation operations
    - Work through addition/subtract multiple/divide with and without round and guard bits
  - Purpose of special bits
    - Round, guard, sticky
  - Why aren't some FP operations associative? Give example
  - Challenges wrt to FP operations (e.g., precision, accumulated errors)